



# **AGE INVARIANT FACE RECOGNITION USING FUZZY LOCAL BINARY PATTERN AND ARTIFICIAL NEURAL NETWORK CLASSIFIER**

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**Abstract-** Several attempts have been made on Age-Invariant Face Recognition (AIFR), but most available algorithms are based on age estimation and aging simulation, which have several limitations; such as lack of robust discriminative features that are stable across ages, need for normal illumination and neutral facial expressions. Hence, there is a need for the development of an improved AIFR system that can handle these shortcomings. In this work, an AIFR system using local-feature based approach was developed. It uses Fuzzy Local Binary Pattern (FLBP) algorithm for feature extraction and Artificial Neural Network (ANN) for classification. Face and Gesture Recognition Research Network (FG-NET) database was used for testing, while Recognition performance was evaluated using recognition accuracy, sensitivity and specificity. Performance evaluation results of the developed system gave 89.44%, 49.80% and 49.77% recognition accuracy, sensitivity and specificity respectively. The system can be deployed in biometric identification systems and surveillance applications where age variations are pervasive.

**Keywords:** Fuzzy, Local Binary Pattern, Periocular, Normalization, Classification

## **1. INTRODUCTION**

Aging in human can be referred to a multidimensional process of physical, psychological, and social change (Bronikowski and Flatt, 2010). With growth and maturity, the human face changes most of its enduring properties (such as shape of cranium, texture, and appearance of the facial skin), acquires new shape and appearance with wrinkles, folds, pouches, discoloration, becomes rougher, leatherier and darker. These physical changes of the face, marks the aging of the face (Bronikowski and Flatt, 2010), and consequently poses a serious challenge in designing facial recognition system that is age invariant. This has led to the development of age invariant face recognition (AIFR) system.

Age related face recognition research has gained attention recently because of its practical applications in authentication and authorization. There are two major approaches to AIFR, which are holistic model based approach (Global approach) and local features based approach (Juefei-Xu, Luu, Savvide, Bui and Suen, 2011). However, most available algorithms are based on age estimation and aging simulation (Ali, Asirvadam, Malik and Aziz, 2013; Park, Tang and Jain, 2011; Ramanathan and Chellapa, 2009). The holistic (global approach) methods to AIFR have shown to be effective thoughwith some drawbacks, while local feature based approach have been gaining attention in recent times (Gong, Li, Lin, Liu and Tang, 2013).

The challenging problem of AIFR is the large intra subjects' variations due to aging (Li, Park and Jain, 2011), such as aging, pose, illumination, and facial expression. In addition, AIFR systems that are based on age estimation and aging simulation have other limitations such as need for normal illumination and neutral facial expressions. Therefore, there is a need for robust approach that can handle these variations and retain high accuracy. A robust feature extraction technique may be useful in handling these variations. This work therefore aimed at developing an age invariant face recognition system using Local Feature Based Approach for feature extraction and neural network for classification.

## **2. LITERATURE REVIEW**

Age-related face recognition methods can be categorized into two: local approaches and holistic (global) approaches. Most holistic approaches try to generate face aging models and build aging functions to simulate or compensate for the aging process (Lanitis, Taylor and Cootes, 1999; Geng, Zhou and Smith-Miles, 2007, Guo, Fu, Dyer and Huang, 2008, Kambhamettu and Mahalingam, 2010). Ali, Asirvadam, Malik and Aziz (2013) proposed a geometrical model based on multiple triangular features for handling the challenge of face age variations that affect the process of face recognition. The system aimed to serve in real time applications where the test images are usually taken in random scales that may not be of the same scale as the probe image, along with orientation, lighting, illumination, and pose variations. Multiple mathematical equations were developed and used in the process of forming distinct subject clusters. The system achieved a maximum classification accuracy of above 99% when the system was tested over the entire FG-NET database.

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Local based approaches for age invariant face recognition have not been well explored. Contrary to holistic face interpretation, most of these local feature based methods are proposed to solve the age estimation problem. These approaches have been reported to overcome the shortcomings of sensitivity, illumination variations and image occlusions. Moreover, age features are usually encoded by local information such as wrinkles on the forehead or at the eye corners (Ling, Soatto, Ramanathanan and Jacob, 2007; Biswas, Aggarwal and Chellappa, 2008; Hasegawa-Johnson, Huang, Liu, Yan, & Zhou, 2008; Fu and Huang, 2008; Li, Park and Jain, 2011). Juefei-Xu, Luu, Savvide, Bui and Suen (2011) investigated age invariant face recognition in FG-NET aging database using unsupervised discriminant projection (UDP) method of subspace learning techniques based on periocular biometrics. In this method, Juefei-Xu et al. (2011) applied preprocessing schemes like pose correction, illumination normalization using Anisotropic Diffusion Model and periocular normalization to obtain age invariant features which uses a fusion of Walsh-Hadamard Transform and Local Binary Pattern to generate local features also used normalized cosine distance measurement, a Nearest Neighbor (NN) classifier as the classifier. Fazli and Ali Heidarloo (2012) proposed discrete wavelet transform and combination wavelet sub-band coefficients and gradient orientation of coefficients for feature representation. Gradient orientation (GO) was proposed for face verification across age progression and has been shown to be insensitive to aging process. Principal Component Analysis (PCA) was applied for feature dimensionality reduction and Euclidean distance was used for recognition. Experimental results show that the proposed method is efficient and it achieved better recognition performance.

### 3. METHODOLOGY

Our approach uses Fuzzy Local Binary Pattern for facial features extraction and Neural Network for classification. The flowchart for the developed age invariant face recognition system is as shown in Figure 1 and the methodology for the implementation of the developed system is as discussed in the following subsections. All the processes involved were implemented using MATLAB(R) 8.1.0.604 (R2013a) version on a 1.65 GHz, 4.00GB RAM, Windows 7, Asus Personal Computer. Performance of the developed AIFR system was evaluated using accuracy, sensitivity and specificity.

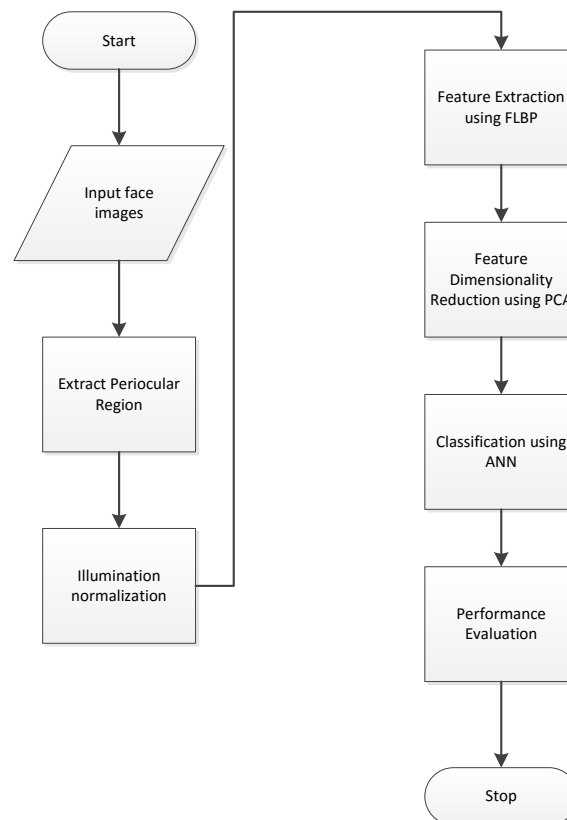


Figure 1. Flowchart of the Age-invariant Recognition System

#### 3.1 Database

The Face and Gesture Recognition Research Network (FG-NET) aging database was used to test the developed system (Fg-net aging database: Face and gesture recognition working group, <http://www-prima.inrialpes.fr/FGnet/>). The FG-NET consists of 1002 aging face images of 82 different subjects between ages 0-69 years. Three hundred images of 50 subjects were randomly selected at different stages of growth, six per individual for ranges 0-11, 12-23, 24-35, 36-47, 48-59 and 60-

69 years. For the training stage, three out of the six images were used for training and the remaining three images were used for testing.

Preprocessing (Periocular Region Extraction and Image Normalization)

The preprocessing stage includes the extraction of the periocular region of the face. The periocular region is believed to be relatively unchanging despite aging. The periocular part of the face images was extracted through cropping and resized to 120 × 120

pixels in PNG (Portable Network Graphics) format(PNG format was used to retain quality after editing). Figure 2 shows examples of extracted periocular regions from two subjects in the database. Illumination normalization comprises three steps: Gamma correction, Difference of Gaussian and Equalization of variation.GammaCorrection is the name of a nonlinear operation used to encode and decode luminance or tristimulus values in video or stillimage systems. Gamma correction is, in the simplest cases, defined by the following power-law expression:

$$V_{out} = AV_{in}^\gamma \tag{1}$$

In Equation (1), the non-negative real input value  $V_{in}$  is raised to the power  $\gamma$  and multiplied by the constant A, to get the output value  $V_{out}$  ...

In the common case of A = 1, inputs and outputs are typically in the range 0–1.

A gamma value  $\gamma < 1$  is sometimes called an encoding gamma, and the process of encoding with this compressive power-law nonlinearity is called gamma compression; conversely a gamma value  $\gamma > 1$  is called a decoding gamma and the application of the expansive power-law nonlinearity is called gamma expansion.In this work, an encoding gamma was adopted.

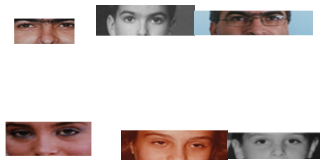


Figure 2: Extracted periocular images for two different subjects with three images each

Illumination normalization was done using preprocessing sequence (PS) approach because it gives better results with reduced aliasing effect. The PS approach consists of three preprocessing steps namely: Gamma Correction of the input image, Difference of Gaussian (DOG) filtering and Equalization of Variation.

$$DoG = (2\pi)^{-\frac{1}{2}} \left[ \sigma_1^{-1} e^{-\frac{x^2+y^2}{(2\sigma_1)^2}} - \sigma_2^{-1} e^{-\frac{x^2+y^2}{(2\sigma_2)^2}} \right] \tag{2}$$

where DoG is the Difference of Gaussian,  $x$  and  $y$  represent the position of the image,  $\sigma_1$  and  $\sigma_2$  is the Gaussian of variance of the image and the narrower portion of the image respectively.

Then, the two-stage contrast equalization employed to re-normalize the image intensities and standardize the overall contrast are given by Equations (3) and (4).

$$I(x, y) = \frac{I(x, y)}{(\text{mean}(|I(x, y)|)^a)^{\frac{1}{a}}} \tag{3}$$

$$\hat{I}(x, y) = \frac{J(x, y)}{(\text{mean}(\min(\tau, |J(x, y)|)^a)^{\frac{1}{a}}} \tag{4}$$

where  $a$  and  $\tau$  are constants,  $I(x, y)$  refers to the pixel in position  $(x, y)$  of the image I. A hyperbolic tangent function in Equation (5) is applied to suppress the extreme values and limit the pixel values in normalized image  $\hat{I}$  to a range of  $[-\tau$  and  $\tau$ ].

$$\hat{I}(x,y) = \tau \tanh\left(\frac{f(x,y)}{\tau}\right) \tag{5}$$

3.2 Feature Extraction

The Fuzzy Local Binary Pattern was adopted for feature representation on each of the periocular face images. Original LBP operator a single LBP code characterizes a 3x3 neighborhood, in the adopted FLBP approach, a neighborhood can be characterized by more than one LBP code. Using the FLBP approach, where two LBP codes characterize a 3x3 neighborhood.

The fuzzification of the LBP approach includes the transformation of the input variables to respective fuzzy variables, according to a set of fuzzy rules. To that direction, two fuzzy rules is introduced to describe the relation between the intensity

values of the peripheral pixel gray level  $g_i$  and the central pixel  $g_{centre}$  of a 3x3 neighborhood as follows:

Rule  $R_0$ : The smaller  $g_i$  is, with respect to  $g_{centre}$ , the greater the certainty that  $d_i$  is 0.

Rule  $R_1$ : The bigger  $g_i$  is, with respect to  $g_{centre}$ , the greater the certainty that  $d_i$  is 1. According to the rules  $R_0$  and  $R_1$ , two membership functions,  $m_0()$  and  $m_1()$ , can be determined. Let function  $m_0()$  define the degree to which  $g_i$  has a smaller grey

value than  $g_{centre}$ , and thus define the degree to which  $d_i$  is 0. As a membership function  $m_0()$  we considered the decreasing function defined in Equation (6) (Iakovidis, Keramidas and Maroulis, 2008).

$$m_0(i) = \begin{cases} \frac{T-g_i+g_{centre}}{2T} & \text{if } g_{centre} - T < g_i < g_{centre} + T \\ 0 & \text{if } g_i \geq g_{centre} + T \\ 1 & \text{if } g_i \leq g_{centre} - T \end{cases} \tag{6}$$

On the other hand, membership function  $m_1()$  defines the degree to which  $g_i$  has a greater grey value than  $g_{centre}$ , and thus define the degree to which  $d_i$  is 1. For both  $m_0()$  and  $m_1()$ ,  $T \in [0,255]$  represents a parameter that controls the degree of fuzziness.

In the FLBP approach, two LBP codes characterized a 3x3 neighborhood. The degree to which each LBP code characterizes a neighborhood, depends on the membership functions  $m_0()$  and  $m_1()$ . For a 3x3 neighborhood, the contribution  $C_{LBP}$  of each LBP code in a single bin of the FLBP histogram is defined as:

$$C_{LBP} = \prod_{i=0}^8 m_{d_i}(i) \tag{7}$$

$d_i \in \{0,1\}$ , and the LBP code can be obtained. For each peripheral pixel,  $d_i$  can be either 0 or 1, with a grade of  $m_0()$  or  $m_1()$

respectively, forming different LBP codes with different contributions in Equation (7). Thus, each 3x3 neighborhood contributes to more than one bin of the FLBP histogram. The total contribution of a 3x3 neighborhood to the bins of an FLBP histogram is:

$$\sum_{LBP=0}^{255} C_{LBP} = 1 \tag{9}$$

Figure 4 shows the original periocular image and the corresponding FLBP Features of the same image.

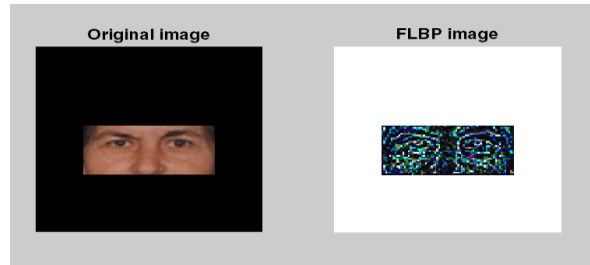


Figure 4: Original Periocular Image and the Corresponding FLBP Feature

### 3.3 Feature Reduction

For better performance of the face recognition system and to solve the problem of high dimensionality of feature space, PCA was employed for feature reduction. Ten features from the FLBP extracted were selected and fed into the ANN classifier.

### 3.4 Feature Classification

Back-propagation Artificial Neural Network (BANN) was used for classification. The back-propagation neural network used is divided into two steps – feed-forward and back-propagation. The selected features were allocated classes (training and test data). The test data was also separated into two groups; clients and impostors for verification. The classification was performed using a similarity based approach. Euclidean distance measurement for classification was used to compute the similarity matrix. Euclidean distance measurement for an  $i$ -dimension space is given as:

$$D(x, y) = \sqrt{\sum_{i=1}^n (x_i - y_i)^2} \quad (10)$$

where  $x$  and  $y$  are the feature vectors that is the training and test features respectively.

The output of the system was used to estimate the confusion matrix and the similarity matrix. The following performance metrics were then estimated: accuracy, sensitivity and specificity were estimated.

#### Performance Evaluation of the Developed System

The following Performance Evaluation method was used to validate the developed system Sensitivity ( $Se$ ) measures the proportion of actual position which is correctly identified.

$$Se(\%) = \frac{TP}{TP + FN} \times 100 \quad (11)$$

Specificity measures the proportion of negatives which are correctly identified.

$$S(\%) = \frac{TN}{TN + FP} \times 100 \quad (12)$$

The measurement of delineation accuracy,  $Acc$ .

$$Acc(\%) = \frac{TP + TN}{TP + TN + FP + FN} \times 100 \quad (13)$$

where TP, TN, FP and FN stand for true positives, true negatives, false positives and false negatives respectively.

## 4. RESULTS AND DISCUSSION

### 4.1 Performance Evaluation

Table 1 shows the recognition accuracy, system sensitivity and the system specificity of the developed system. The developed system gave 89.44% recognition accuracy, sensitivity of 49.80% and the system specificity of 49.77%. This is a better performance compared to other method, Discrete Wavelet Transform (DWT) - Gradient Orientation (GO) and Scale Invariant Feature Transform (SIFT), which gave 59.09% and 65.3% recognition accuracy respectively. Figure 5 shows the statistical evaluation of the AIFR methods with their recognition performances. The improved recognition of the developed system can be attributed to the use of FLBP for feature extraction and the fact that only periocular regions of the faces were used for recognition.

Table 1: Results of the Developed System

Metric	FLBP-based Approach
Accuracy	89.44%
Sensitivity	49.80%

Specificity 49.77%



Figure 5. Recognition Accuracy of the Developed System

## 5. CONCLUSION AND RECOMMENDATION

### 5.1 Conclusion

In this work, an improved system for Age Invariant Face Recognition using Local-Feature Based Approach (LFBA) and back-propagation Artificial Neural Network classifier was developed. Face and Gesture Recognition Research Network (FG-NET) datasets were adopted for testing, while the system was implemented using Matrix Laboratory 8.1.0.604 (R2013a) version. Performance evaluation gave 89.44% accuracy, which is some improvement over existing methods.

### 5.2 Recommendation

In the nearest future, an improvement can be made on this work by improving on the feature extraction technique, for example, a hybrid feature extraction technique can be adopted.

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